

Math 250-Section #3 Final

This exam has 12 questions, for 100 points. [The spreadsheet will scale to 200 points.] Answers must be explained to be acceptable—part credit to be given for good effort. There is a page with some formulas at the back and a scratch page. Good luck!

Name: _____

1. [10 pts] Consider the following 4×3 matrix A and its reduced row echelon form $\text{rref}(A)$:

$$A = \begin{bmatrix} 1 & 1 & 7 \\ 1 & 2 & 10 \\ 1 & 3 & 13 \\ 1 & 4 & 16 \end{bmatrix}, \quad \text{rref}(A) = \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

- (a) $\dim \text{Col}(A) = \underline{2}$. Give a set of column vectors in \mathbf{R}^4 that is a basis for $\text{Col}(A)$.

$$\left[\begin{array}{c} | \\ | \\ | \\ | \end{array} \right] \left[\begin{array}{c} 1 \\ 2 \\ 3 \\ 4 \end{array} \right]$$

- (b) Write each column of A not in your basis as a linear combination of the basis vectors.

$$\begin{bmatrix} 7 \\ 10 \\ 13 \\ 16 \end{bmatrix} = 4 \begin{bmatrix} | \\ | \\ | \\ | \end{bmatrix} + 3 \begin{bmatrix} | \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

- (c) $\dim \text{Null}(A) = \underline{1}$. Give a set of column vectors in \mathbf{R}^3 that is a basis for $\text{Null}(A)$.

$$\begin{bmatrix} -4 \\ -3 \\ 1 \end{bmatrix}$$

(d) $\dim \text{Row}(A) = \underline{2}$ and $\dim \text{Null}(A^T) = \underline{2}$.

(e) Suppose $\mathbf{y} \in \text{Col}(A)$ and $\mathbf{z} \in \text{Null}(A^T)$. Prove that $\mathbf{y}^T \mathbf{z} = 0$.

$\mathbf{z} \in \text{Null}(A^T)$ means

$$A^T \mathbf{z} = \mathbf{0}$$

so each row of A^T is
 \perp to \mathbf{z} . But ~~cols~~_{rows} of A^T
are columns of A

2. [10 pts] Let

$$A = \begin{bmatrix} 1 & -1 & -1 \\ 2 & -1 & -1 \\ 4 & -3 & -3 \end{bmatrix}$$

- (a) Find a basis of its nullspace.
 (b) Find a basis of its row space.
 (c) Is

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

a vector in the nullspace of A ?

- (d) Is there a vector v so that

$$Av = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}?$$

- (e) Could v be found using Cramer's rule?

Answer:

$$\begin{array}{ccc|ccc} 1 & -1 & -1 & 1 & -1 & -1 \\ 2 & -1 & -1 & 0 & 1 & 1 \\ 4 & -3 & -3 & 0 & 1 & 1 \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array}$$

a) $\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$

b) $(1, 0, 0), (0, 1, 1)$

c) not invertible \uparrow a)

:

d) no, b/c $\det A = 0$

3. [10 pts] The matrix $A = \begin{bmatrix} 2 & 2 & 0 \\ 2 & 3 & 2 \\ 0 & 2 & 4 \end{bmatrix}$ has eigenvalues $\lambda_1 = 0$, $\lambda_2 = 6$, and $\lambda_3 = 3$. Let \mathbf{u}_1 , \mathbf{u}_2 , and \mathbf{u}_3 be corresponding eigenvectors (normalized to have length one).

(a) Since A is symmetric and λ_1 , λ_2 , and λ_3 are all different, it follows that

$$\mathbf{u}_1 \cdot \mathbf{u}_2 = \mathbf{u}_1 \cdot \mathbf{u}_3 = \mathbf{u}_2 \cdot \mathbf{u}_3 = \underline{0}$$

$u_i \perp u_j$
 $i \neq j$

(b) The 3×3 matrix $P = [\mathbf{u}_1 \mid \mathbf{u}_2 \mid \mathbf{u}_3]$ satisfies

$$P^T P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (\text{fill in the entries of this } 3 \times 3 \text{ matrix}).$$

(c) Let P be the matrix of normalized eigenvectors from (b). Then $A = PDP^T$, where

$$D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad (\text{fill in the entries of this } 3 \times 3 \text{ matrix}).$$

(d) Verify that the characteristic polynomial of A is $-t(t-3)(t-6)$ by using a cofactor expansion of an appropriate determinant. Give details.

$$\begin{vmatrix} 2-t & 2 & 0 \\ 2 & 3-t & 2 \\ 0 & 2 & 4-t \end{vmatrix} = \text{do it!}$$

(Problem 3 continues on the next page)

(Continuation of Problem 3)

(e) Calculate eigenvectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 for A corresponding to the eigenvalues $\lambda_1 = 0$, $\lambda_2 = 6$, and $\lambda_3 = 3$. (you don't have to normalize these vectors). After calculating each eigenvector \mathbf{v}_i , verify that $A\mathbf{v}_i = \lambda_i\mathbf{v}_i$.

Recall that

$$A = \begin{bmatrix} 2 & 2 & 0 \\ 2 & 3 & 2 \\ 0 & 2 & 4 \end{bmatrix}$$

nullspaces of $A - \lambda I$

$$\lambda = 0$$

$$\begin{array}{ccc|c} 2 & 2 & 0 & 0 \\ 2 & 3 & 2 & 0 \\ 0 & 2 & 4 & 0 \end{array} \rightarrow$$

$$\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 2 & 2 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \rightarrow$$

$$\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array}$$

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$$

4. [8 pts] Let $u = [2, 1, 1]$, $v = [1, 0, 1]$ and $w = [0, 1, 1]$ be vectors of \mathbb{R}^3 .

(a) What does it mean to say that a set u_1, \dots, u_n of vectors is linearly independent?

(b) Are u, v, w above linearly independent?

(c) If the vector $\alpha = [3, 1, -1]$ lies in the span of u, v, w , express it as a linear combination of these vectors.

Answer:

(a) Look up def'n in text

(b)
$$\begin{array}{ccc|ccc} 2 & 1 & 0 & & & \\ 1 & 0 & 1 & & & \\ 1 & 1 & 1 & & & \end{array} \xrightarrow{R_1 \leftrightarrow R_2} \begin{array}{ccc|ccc} 1 & 0 & 1 & & & \\ 2 & 1 & 0 & & & \\ 1 & 1 & 1 & & & \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & 0 & 1 & & & \\ 0 & 1 & -2 & & & \\ 0 & 1 & 0 & & & \end{array} \rightarrow \begin{array}{ccc|ccc} 1 & 0 & 0 & & & \\ 0 & 1 & 0 & & & \\ 0 & 0 & 1 & & & \end{array}$$

\therefore lin. ind.

(c) Solve

$$\begin{array}{ccc|c} 2 & 1 & 0 & 3 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 1 & -1 \end{array}$$

5. [8 pts] Let $Ax = \mathbf{b}$ be a system of linear equations.

(a) What does it mean to say that the **system is CONSISTENT**?

(b) Are all systems consistent? [If not, give example.]

(c) Explain the following fact: The system is consistent only if the matrix A and the extended matrix $[A|\mathbf{b}]$ have the same rank.

Answer:

Look up in text book

6. [8 pts] (a) Find the determinant of the matrix

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & 1 \\ 3 & t & t \end{bmatrix}$$

(b) Determine the values of t for which the matrix is invertible.

Answer: (a) cofactor expansion along row #1

$$\det A = 1 \begin{vmatrix} 2 & 1 \\ t & t \end{vmatrix} - 2 \begin{vmatrix} 2 & 1 \\ 3 & t \end{vmatrix} - \begin{vmatrix} 2 & 2 \\ 3 & t \end{vmatrix}$$

$$= t - 2(2t - 3) - 2t + 6 = -5t + 12$$

$$A \text{ inv} \iff \det A \neq 0$$

$$-5t + 12 \neq 0$$

$$\therefore t \neq \frac{12}{5}$$

7. [8 pts] Given the matrix

$$A = \begin{bmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix},$$

- (a) Find its inverse.
 (b) Find the determinant of $2(A)^2$.
 (c) Find the determinant of $AA^T A^{-1}$.

Answer:

(a) Do algorithm

$$\left[\begin{array}{ccc|ccc} 0 & 1 & 2 & 1 & 0 & 0 \\ 1 & 2 & 3 & 0 & 1 & 0 \\ 1 & 4 & 9 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\text{rref}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right] A^{-1}$$

$$\begin{aligned} (b) \quad \det A &= -1 \begin{vmatrix} 1 & 2 \\ 1 & 9 \end{vmatrix} + 2 \begin{vmatrix} 1 & 2 \\ 1 & 4 \end{vmatrix} \\ &= -6 + 4 = -2 \\ \det 2A^2 &= 2^3 \cdot \det(A)^2 \\ &= 32 \end{aligned}$$

$$\begin{aligned} (c) \quad \det AA^T A^{-1} &= \det(A) \det(A^T) \det A^{-1} \\ &\quad \swarrow \text{cancel} \\ \det A^T &= \det A \\ \therefore &= -2 \end{aligned}$$

8. [9 pts] Let S be a subset of \mathbb{R}^5 . Explain:
- (a) When is S a subspace?
 - (b) What is a basis of S .
 - (c) Why the dimension of S cannot be larger than 5?
 - (d) If S is the solution set of the system of equations

$$A \cdot x = b,$$

when is S a subspace?

Answer:

(a), (b), (c) Look up in text

(d) If S is a subspace
and x_1 & x_2 are sol^s,
then $x_1 + x_2$ must be a
solution

$$A(x_1 + x_2) = b \quad ?$$

$$Ax_1 + Ax_2 = b \quad ?$$

$$b + b = b \quad \therefore \text{only}$$

happens when $b = 0$

9. [8 pts] (a) Consider the matrix $\mathbf{u} = \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix}$. Find the matrix $A = \mathbf{u}\mathbf{u}^T$

and show that it has rank 1.

(b) Consider the nonzero matrix $\mathbf{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$. Find the matrix $B = \mathbf{v}\mathbf{v}^T$

and show that it has rank 1.

(c) If $\mathbf{v} \neq \mathbf{0}$, show that $\mathbf{v}\mathbf{v}^T$ has always rank 1.

Answer:

(a)

$$A = \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} \cdot [1 \ 2 \ 3] = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$

columns are multiples of first

(b) Same in general

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} [a, b, c] = \begin{bmatrix} a^2 & ab & ac \\ ab & b^2 & bc \\ ac & bc & c^2 \end{bmatrix}$$

If, say, $a \neq 0$, 2nd & 3rd cols are

mults of first.

Same argument if $b \neq 0$ or $c \neq 0$

10. [8 pts] (a) Find an orthogonal matrix S such that $S^{-1}AS$ is diagonal, where

$$A = \begin{bmatrix} 10 & 3 \\ 3 & 2 \end{bmatrix}.$$

(b) Use Part (a) to decide whether the equation $10x^2 + 6xy + 2y^2 = 18$ represents an ellipse, a parabola or a hyperbola.

Answer:

Done off u

11. [8 pts] Let W be the subspace of \mathbf{R}^3 spanned by the vector $\mathbf{u} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

(a) Let $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$. Find the orthogonal projection \mathbf{w} of \mathbf{v} onto W .

$$\text{proj}_W \mathbf{v} = \frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} = \frac{4}{6} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

(b) Suppose $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ is in W^\perp . Write down the equation satisfied by

x_1, x_2, x_3 . Use this to find a basis for W^\perp .

Answer:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} = x_1 + 2x_2 + x_3 = 0$$

free row

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

✓
basis
of W^\perp

12. [5 pts] Explain the following fact: For ANY square matrix A , the matrix $B = AA^T$ is diagonalizable.

Answer:

$B = AA^T$ is always
symmetric

$$\begin{aligned} B^T &= (AA^T)^T = (A^T)^T A^T \\ &= AA^T \end{aligned}$$

used property: transpose of a
product is product of
transposes in reverse order

Scratch page

The routine to obtain a basis that is orthogonal from another basis
[Gram–Schmidt process]: Input basis $S = \{u_1, \dots, u_n\}$

Step 1: Set $v_1 = u_1$

Step 2: Compute v_2, \dots, v_n successively, one at a time, by

$$v_i = u_i - \left(\frac{u_i \cdot v_1}{v_1 \cdot v_1}\right)v_1 - \left(\frac{u_i \cdot v_2}{v_2 \cdot v_2}\right)v_2 - \dots - \left(\frac{u_i \cdot v_{i-1}}{v_{i-1} \cdot v_{i-1}}\right)v_{i-1}$$

Step 3: Set

$$w_i = \frac{v_i}{\|v_i\|}$$

Then $T = \{w_1, \dots, w_n\}$ is an orthonormal basis.

Quadratic Equation: The roots of

$$ax^2 + bx + c = 0, \quad a \neq 0$$

are:

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$